

"An Open Approach to a Media Exchange Layer"

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05/05/2025

Recap since VidTrans24

- Software defined production tools using standard IT (CPU/GPU) and IP technologies are already here and used today by many customers
- ► Tier-1 Live Sports Production
- Global Sporting Events
- Major Broadcast Infrastructures
- However, with these new tools, new challenges arise !









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The industry challenge !









* EBU – The Dynamic Media Facility Reference Architecture

Layering – the building blocks



Plane running on every compute instance, providing point of contact. Communicates live control requests to planes and services below and reports back logging, channel status and overall server health

This Plane performs any required video, audio or ancillary processing

This Plane hosts various services responsible for depacketizing and writing receiver video, audio and ancillary data, quantising it into video frames for processing, before reading processed data from memory and packetizing it into senders.





App with local shared memory





ST2110, NDI, SRT type RX/TX

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Shared memory across apps (same host)





ST2110, NDI, SRT type RX/TX

Memory Reader/Writer



Stream Transcoder On / Off into memory (same host)





ST2110, NDI, SRT type RX/TX

Memory Reader/Writer



Shared memory across multiple apps (same host)





ST2110, NDI, SRT type RX/TX

Memory Reader/Writer



Shared memory across multiple compute nodes



Shared memory across multiple compute nodes



Intelligent memory store, self describing media (metadata)

Video (frame) store:

- Packing format YUV422P
- 16-bit 4:2:2 with separate Y, U/Cb and V/Cr planes
- No interleaving of Y and C, or Cb and Cr, fully planar
- Initially 4:2:2 but easy to extend to 4:4:4 (if required) and add Alpha support
- Arrangement in memory:
 - Frame 0 Y plane, U plane, V plane
 - Frame 1 Y plane, U plane, V plane, etc...







> Metadata is stored per frame, and has the following structure:

- int32_t Width; // the number of active pixels per line
- int32_t Height; // the number of active lines
- int32_t FieldRate; // integer representation, i.e. 59.94 = 59
- ScanType scan; // field/frame scan type
- ScanType origScan; // original field/frame scan type (prior to deinterlacing)
- VidDataFormat Format; // the frame data format (i.e. YUV422P)
- uint64_t Timestamp; // source timestamp converted to PTP time
- Rectangle ActiveArea; // the active area of the image within the frame





> Metadata is stored per frame, 'Scan' type is enumerated as follows:

- SCAN_UNDEFINED = 0,
- SCAN_PROGRESSIVE, // full progressive frame
- SCAN_INTERLACED_TOP_F1, // interlaced, first field, top lines
- SCAN_INTERLACED_BOT_F1, // interlaced, first field, bottom lines
- SCAN_INTERLACED_TOP_F2, // interlaced, second field, top lines
- SCAN_INTERLACED_BOT_F2, // interlaced, second field, bottom lines
- SCAN_SEGMENTED, // progressive segmented frame





> Metadata is stored per frame, The 'Active Area' rectangle is defined as:

- int32_t Xstart; // first active pixel
- int32_t Ystart; // first active line
- int32_t Xend; // pixel after the last active pixel
- int32_t Yend; // line after the last active line
- So {0, 0, 1920, 1080} would be a full 1080p active frame





> Audio store:

- 32-bit integer (2's complement) audio samples, MSB aligned
- Memory layout is a 2D array: channels x samples
- Samples are addressed in the store using the LSBs of the RTP timestamp (which updates at sample rate)
- Store could be any size as long as it's a power of 2
- Different area of the shared memory has the metadata for each channel, this allows the different channels to have different characteristics (sample rate, bit depth etc.)
- For both video and audio stores, you need a mechanism to indicate when the data is stale, or you need the writer to clear the store when the input is lost (Read black frames and silence, for example)







Ancillary Data store:

- Ancillary data is video frame aligned, so the store is 3-dimensional (streams x frames x packets)
- Within the store, each packet keeps all its RFC-8331 data:
- **uint8_t yc**; // C: 1 bit
- **uint16_t lineNumber**; // t Line_Number: 11 bits
- uint16_t horzOffset; // Horizontal_Offset: 12 bits
- **uint8_t streamFlag**; // S (Data Stream Flag): 1 bit
- uint8_t streamNumber; // StreamNum: 7 bits







> Ancillary Data store:

- Ancillary data is video frame aligned, so the store is 3-dimensional (streams x frames x packets)
- Within the store, each packet keeps all its SMPTE ST291-1 data:
- **uint8_t did**; // data identification
- uint8_t sdid_dbn; // secondary data identification (type 2) or data block number (type 1)
- **uint8_t dc**; // the count of user data words
- **uint16_t udw[255]**; // user data, up to 255 10-bit words
- **uint16_t checksum**; // 9-bit checksum of DID, SDID, DC and UDW





Layering – the building blocks





* EBU – The Dynamic Media Facility Reference Architecture

Understanding the 'Upper' layers

- > Multi-vendor applications (Live and non-live media functions)
- > Orchestration central container registry, provisioning / scheduling of compute and network
- > Roles and Permissions (don't forget to clean-up orphan services and garbage)
- > Well documented API (open source)
- > Security first class citizen by design (intra service communications and external API's)





Understanding the 'Lower' layers

- > Built on containerised infrastructure (Docker, Kubernetes)
- Compute (CPU x86 / Arm and GPU discrete and integrated)
- > Network topology North / South (stream transport formats) and East / West (memory sharing)
- > Multi-vendor solution Nvidia Holoscan, Intel Tiber, etc. (discrete and clustered nodes)
- > Private and Public cloud linear expansion (cloud native, not lift and shift)
- > Embrace the use of HPC technologies such as Libfabric (RoCE, EFA)







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Conclusions

- > Built for the future, not inherently built on legacy (v210 10-bit video is a good starting point)
- AV media functions should not be grounded by the lowest common denominator i.e. Audio and Video, Audio only, Video only – not one size fits all (different applications, have different needs – i.e. latency)
- > Convergence is inevitable live and non-live workloads within the same infrastructure
- > Standardisation will slow the progress an open-source approach is needed (Apache 2 ?)
- > Call to action to the industry please get actively involved in the EBU work around the DMF
- Important customer projects are here and are being planned (time critical, no time to lose).



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Thank you !

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